



Albany: A Trilinos-based code for Ice Sheet Simulations and other Applications

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**Deployment and Application of Technologies
provided by the FASTMath Institute**

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Support from:



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National
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What is the Albany Code?

- Finite Element Code
 - Implicit
 - Unstructured Grid
 - Massively Parallel
- Demonstrates Component-Based Code design
 - Libraries
 - Abstract Interfaces
 - Pretty good Software Engineering (for CSE)
- Embedded Analysis Capabilities
 - Automatic Differentiation;
 - Sensitivity Analysis; Stability Analysis; Optimization; UQ



Who is the targeted Albany customer base?

➤ **CSE.**



Albany is built on Trilinos: Leveraging code, software, and expertise



Analysis Tools
(*black-box*)

Optimization
UQ (sampling)
Parameter Studies
Bayesian Calibration

Analysis Tools
(*embedded*)

Nonlinear Solver
Time Integration
Continuation
Sensitivity Analysis
Stability Analysis
Optimization
UQ Solver

Linear Algebra

Data Structures
Iterative Solvers
Direct Solvers
EigenSolver
Preconditioners
Multi-Level Methods

Mesh Tools

Mesh Database
Mesh I/O
PARTITIONING
Load Balancing
Adaptivity

Derivative Tools

Derivatives
Sensitivities
Adjoint
UQ Propagation



Software Quality

Version Control
Regression Testing
Configure / Build System
Test Harness / Dashboard
Continuous Integration

Utilities

Input File Parser
Parameter List
Memory Management

Discretizations

Discretization Library
Field Manager

NextGen Architectures

Data Structures
Programming Model

SciDAC Institutes and ASCR Support

Several Key Components

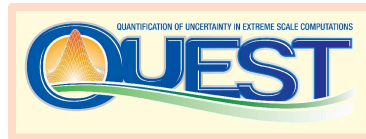
Analysis Tools
(*black-box*)

Optimization

UQ (sampling)

Parameter Studies

Bayesian Calibration



IDEAS
productivity

Software Quality

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(*embedded*)

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Discretizations

Discretization Library

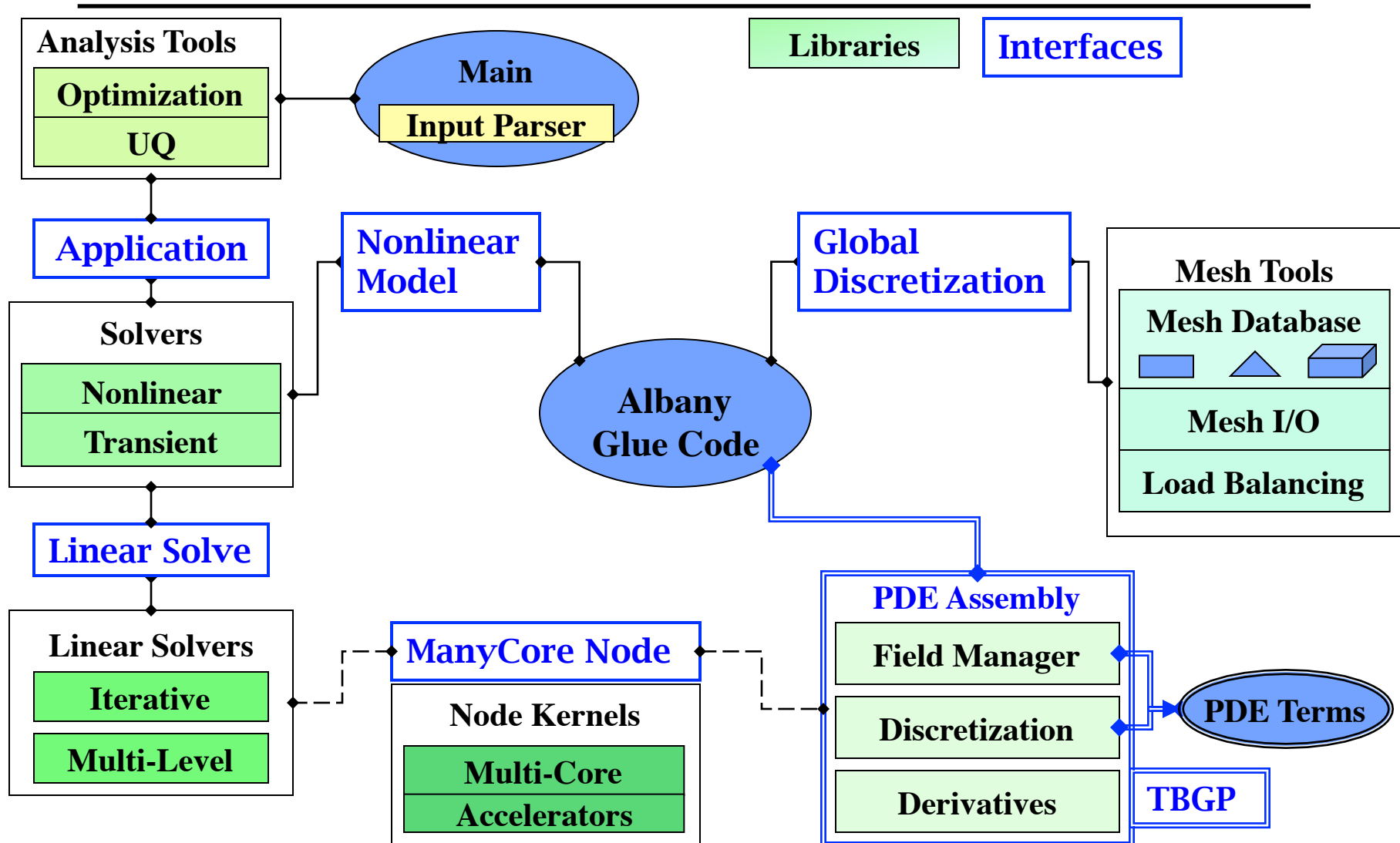
Field Manager

NextGen Architectures

Data Structures

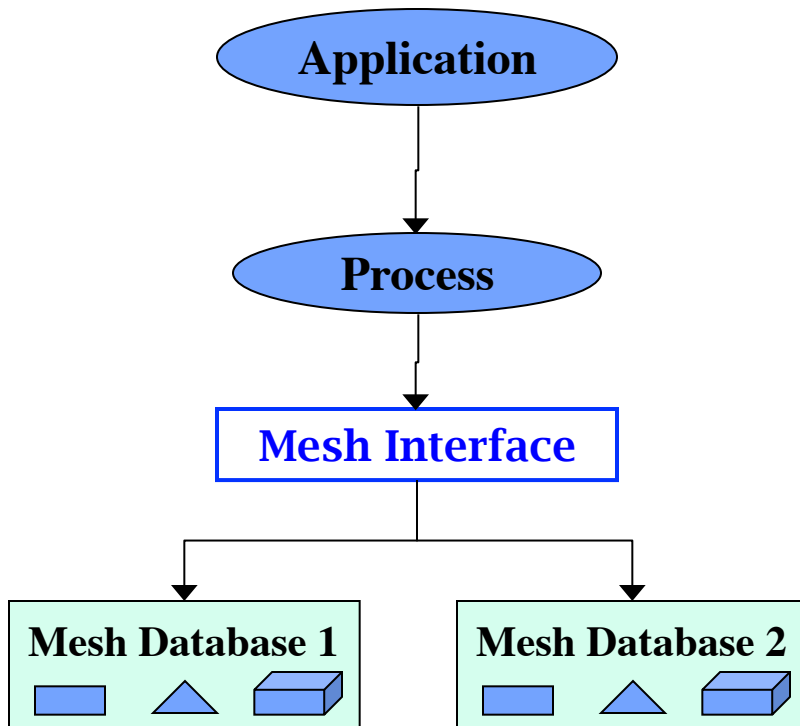
Programming Model

Well-Designed Interfaces make Component-Based Code Design a Scalable Endeavor

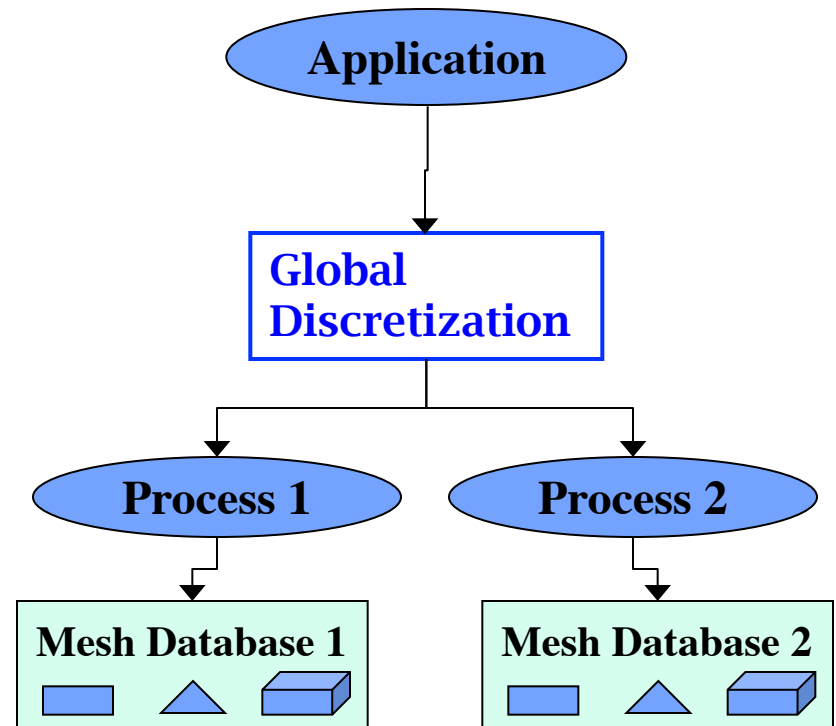


Interface Design: *What does Albany use for a Mesh Interface?*

1. Mesh Interface Design



2. Global Discretization Design

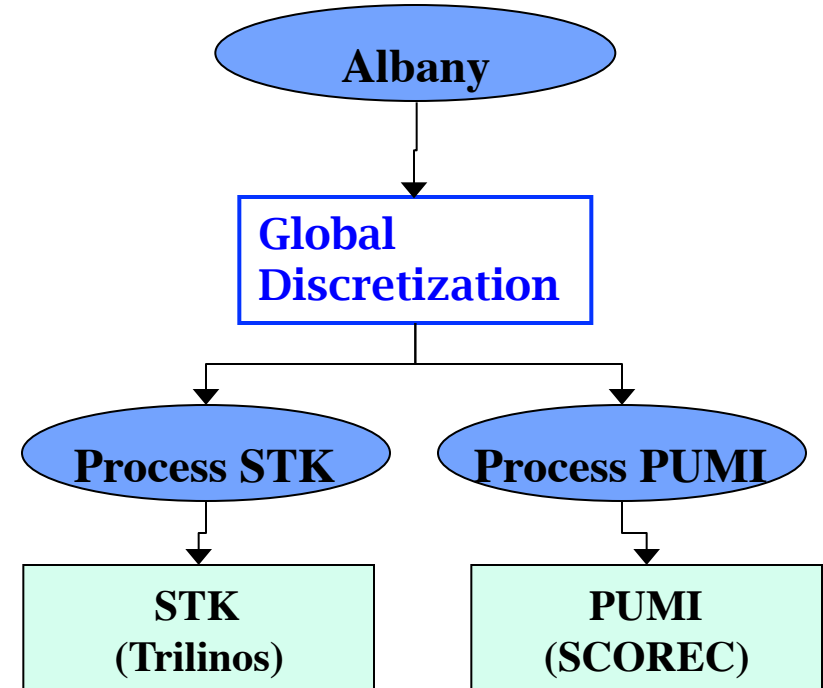


Interface Design: Design of Global Discretization Interface

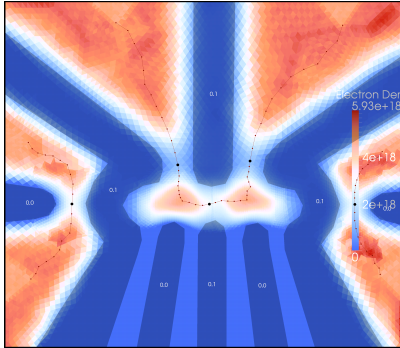
Global Discretization Design

Global Discretization:

- `getCoordinates()`
- `getConnectivity()`
- `getOwnedUnknownMap()`
- `getOverlapUnknownMap()`
- `getJacobianGraph()`
- `getSolution()`
- `writeSolution(x)`

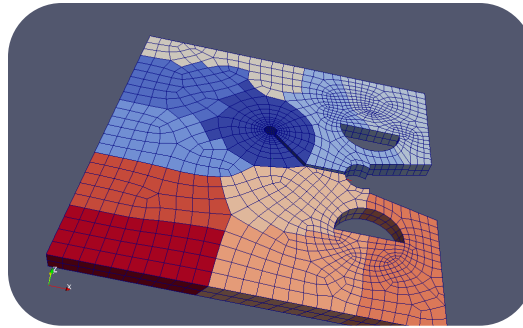


Albany is the Vehicle for Several Application and Algorithm Projects



QCAD:

- Quantum Dot Design

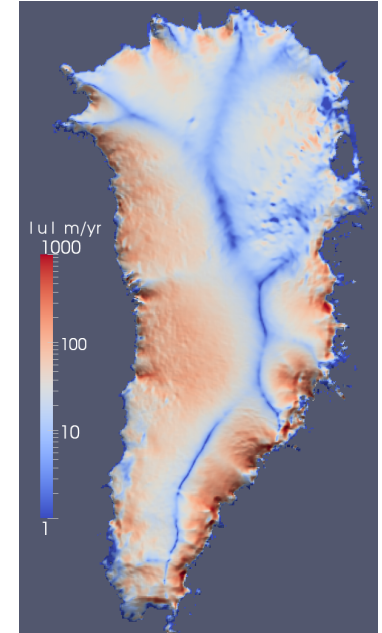


LCM:

- Large Deformation Mechanics
- Failure/Fracture
- Multi-Scale Modeling

Algorithm efforts developed/tested in Albany

1. Mesh Adaptive Loop *Following Talk -- Granzow*
2. Embedded UQ
3. Adjoint Gradients with AD
4. Reduced Order Modeling
5. Topological Optimization
6. Performance-Portable Finite Element Assembly



FELIX:

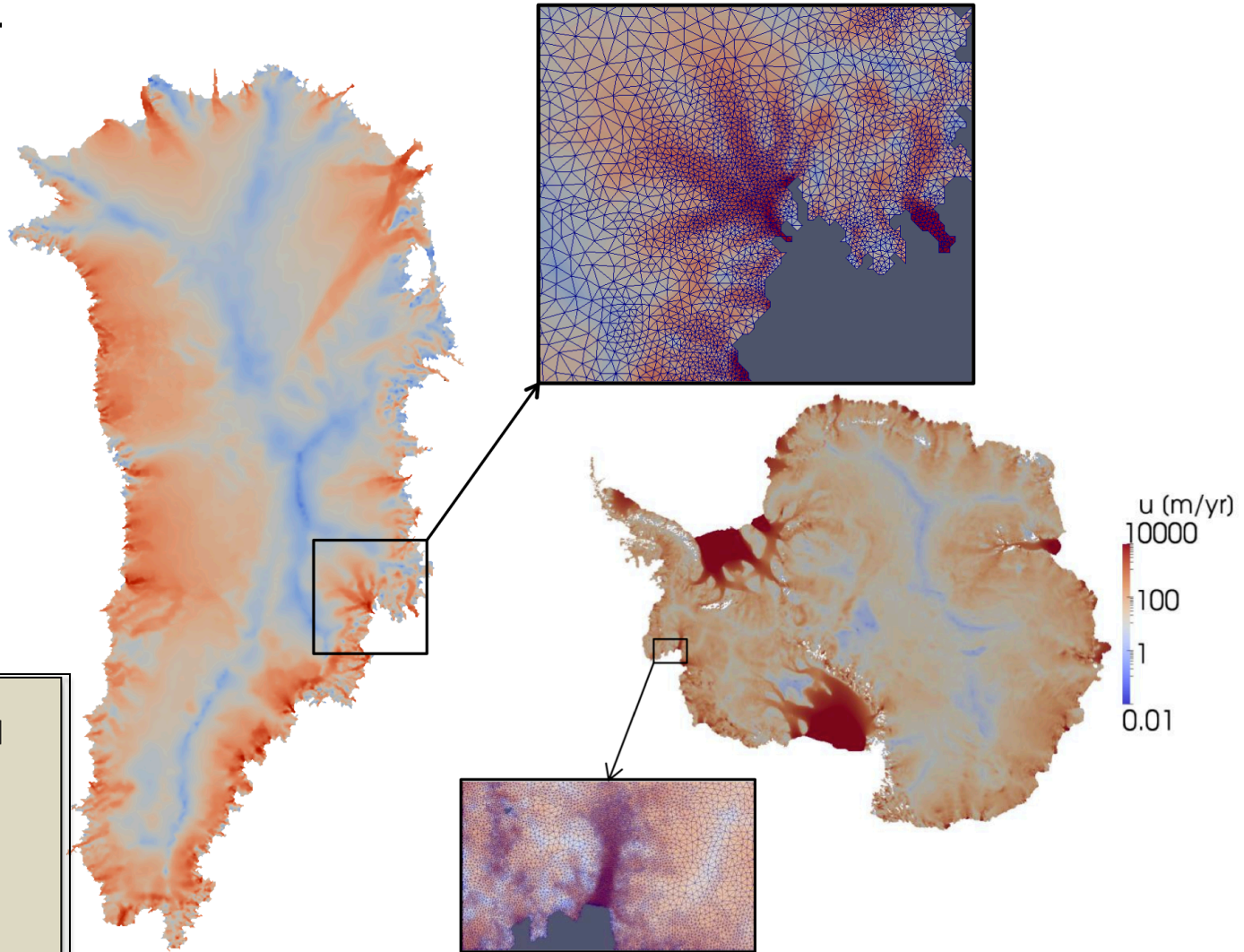
- Ice Sheets

Albany/FELIX code is Supported by PISCEES SciDAC

- Unstructured Grid
- 3D, 2 PDEs
- Steady
- Inversion
- Calibration
- Links under ACME Earth System Model

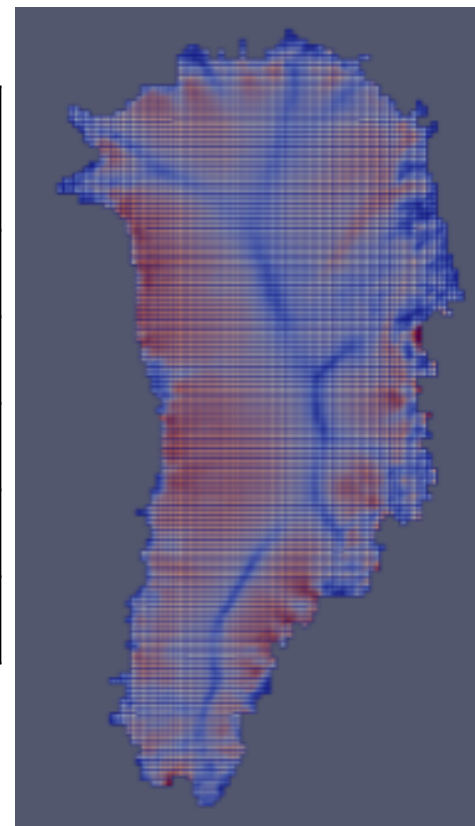
Nonlinear Stokes' Model for Ice Sheet Stresses

$$\begin{aligned} -\nabla \cdot (2\mu\dot{\epsilon}_1) &= -\rho g \frac{\partial s}{\partial x} \\ -\nabla \cdot (2\mu\dot{\epsilon}_2) &= -\rho g \frac{\partial s}{\partial y} \end{aligned}$$



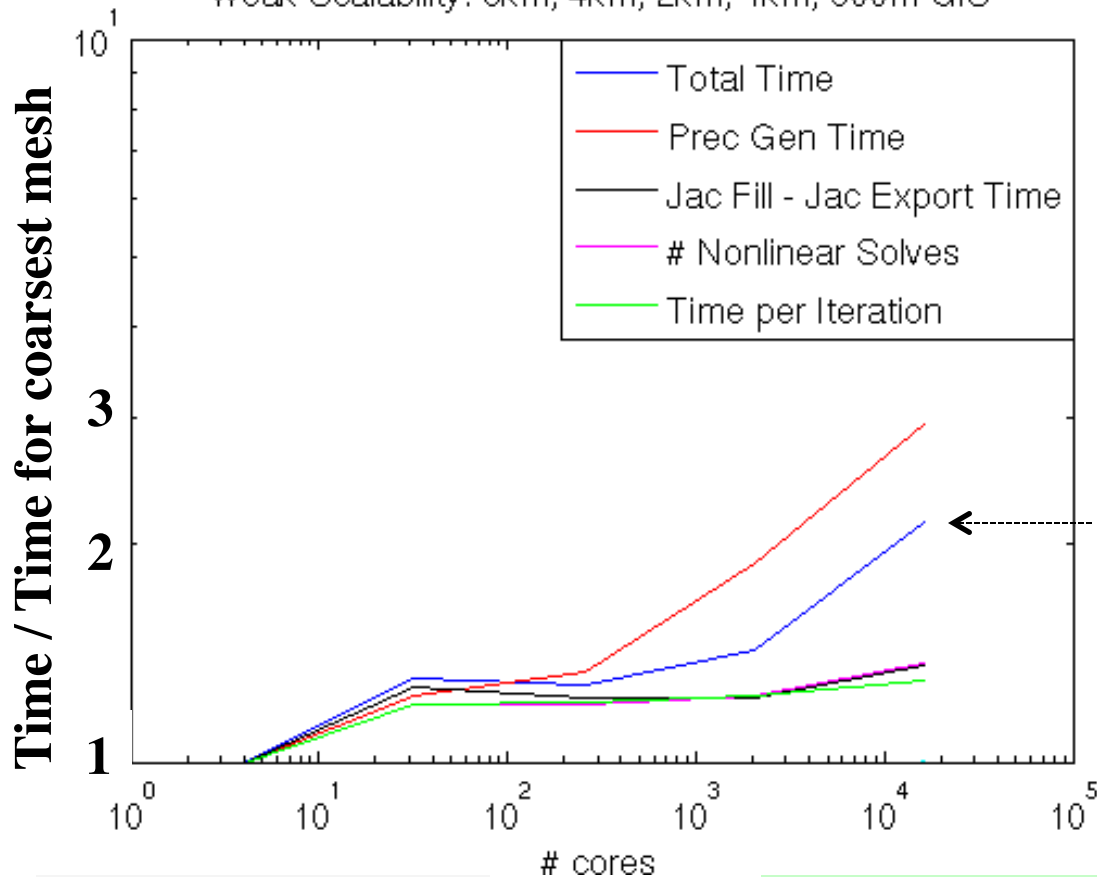
Albany/FELIX: Verification and Mesh Convergence

Horiz. res.\vert. layers	5	10	20	40	80
8km	2.0e-1				
4km	9.0e-2	7.8e-2			
2km	4.6e-2	2.4e-2	2.3e-2		
1km	3.8e-2	8.9e-3	5.5e-3	5.1e-3	
500m	3.7e-2	6.7e-3	1.7e-3	3.9e-4	8.1e-5



Albany/FELIX: Weak Scalability

Weak Scalability: 8km, 4km, 2km, 1km, 500m GIS

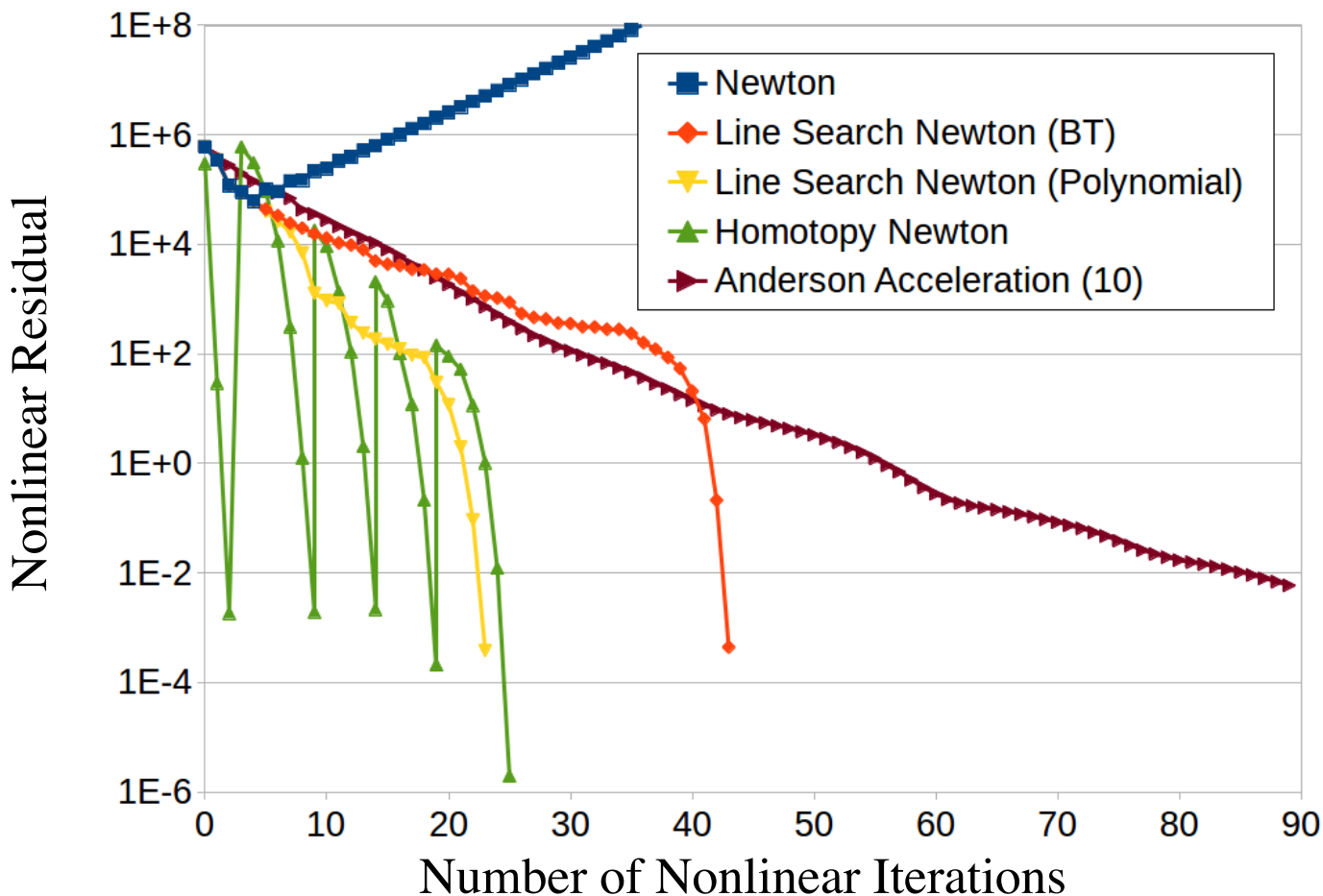


4 cores
334K dofs
8 km Greenland,
5 vertical layers

16,384 cores
1.12B dofs
0.5 km Greenland,
80 vertical layers

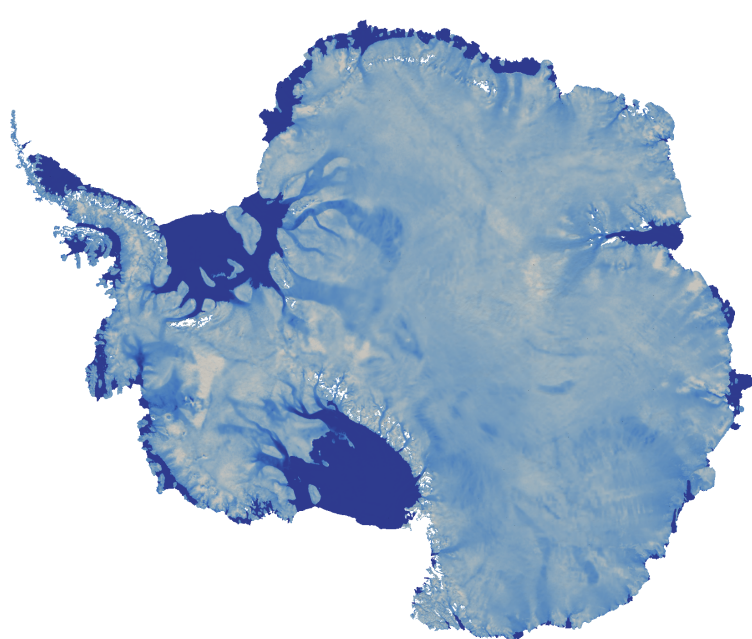
Nonlinear Solvers Robustness is Critical: Land Ice Solver Inside of Climate Model

$$\mu = \frac{1}{2} A^{-\frac{1}{n}} \left(\frac{1}{2} \sum_{ij} \dot{\epsilon}_{ij}^2 + \gamma \right)^{\left(\frac{1}{2n} - \frac{1}{2}\right)} \quad \gamma = 10^{-10}$$

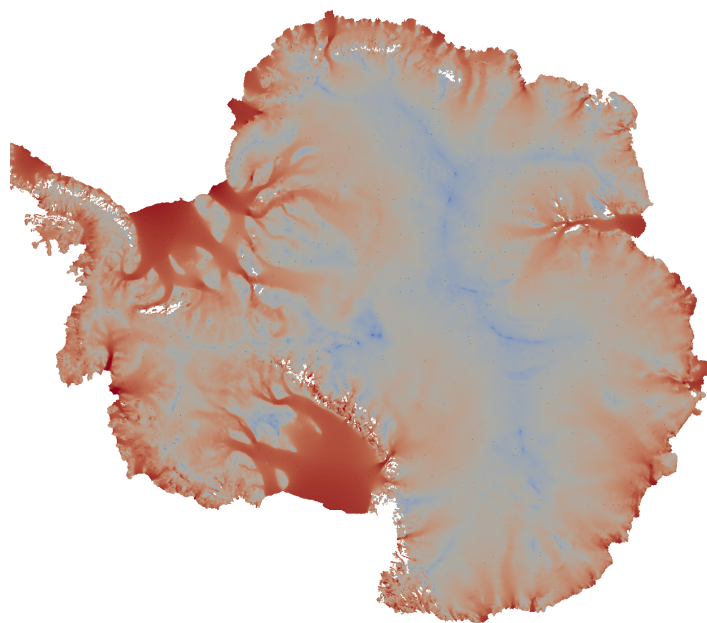


Ice Sheet Initialization: Invert for Basal Sliding Coefficient to Match Observations

Objective functional:
$$\mathcal{J}(\mathbf{u}(\beta), \beta) = \int_{\Sigma} \frac{1}{\sigma_u^2} |\mathbf{u} - \mathbf{u}^{obs}|^2 ds + \alpha \int_{\Sigma} |\nabla \beta|^2 ds$$



beta
150
100
10
1
0.1
0.01

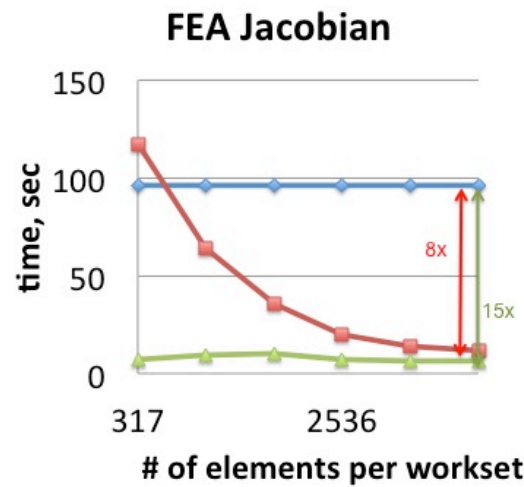
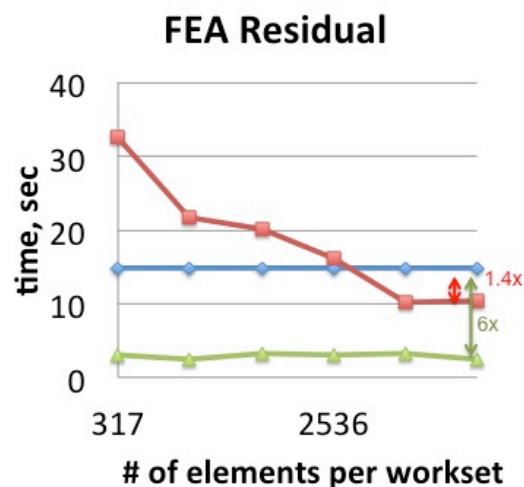
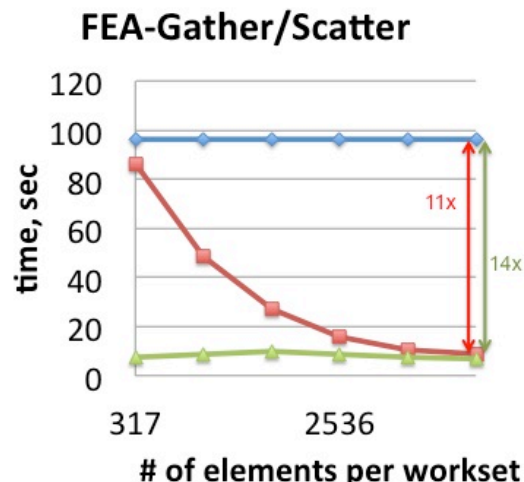
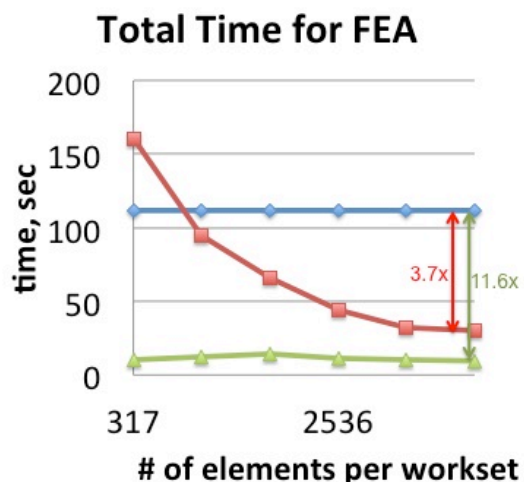


$|u|$
3e+03
100
1
0.01

Inverted for 700K Parameters

**Developed General Purpose Code for Adjoint-Based Gradients
using Automatic Differentiation (Perego, Phipps)**

Finite Element Assembly Refactored to use Kokkos Programming Model



— Serial — CUDA — OpenMP



Conclusion: The SciDAC Vision Can be Successful

Using many libraries requires good software design and practices.

Albany/FELIX code leverages code (expertise):

- Multi-Level Preconditioning code and research (Tuminaro)
- Nonlinear Solver code and research (Pawlowski)
- Adjoint-Based Inversion (Perego, Phipps, Ridzal, Kouri)
- Performance-Portable FE Assembly (Demeshko)
- ✦ Adaptivity
- ✦ Embedded UQ
- ✦ Bayesian Calibration

Acknowledgements: FASTMath, PISCEES, ATDM, OLCF
~30 other Trilinos/Albany/Dakota developers